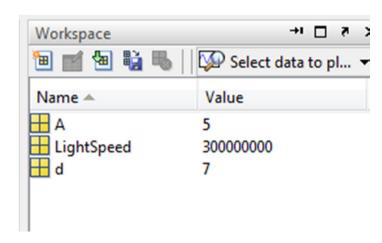
# Lecture 2: Variables, Vectors and Matrices in MATLAB

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#### Variables in MATLAB

- Just like other programming languages, you can define variables in which to store values.
- All variables can by default hold matrices with scalar or complex numbers in them.
- You can define as many variables as your PC memory can hold.
- Values in variables can be inspected, used and changed
- Variable names are casesensitive, and show up in the Workspace.



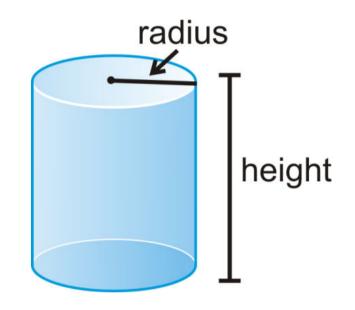
## Variables

- You can change the value in the variable by over-writing it with a new value
- Remember that variables are case-sensitive (easy to make a mistake)
- Always left-to right>> variable = expression

```
>> b = 12
    12
>> b = 14
    14
>> B = 88
    88
>> c = a + b
    21
>> c = a / b
    0.5000
```

## Exercise

- Develop MATLAB code to find Cylinder volume and surface area.
- Assume radius of 5 m and height of 13 m.



$$V = \pi r^2 h$$

$$A = 2\pi r^2 + 2\pi rh = 2\pi r(r+h)$$

## Solution

```
>> r = 5
>> h = 13
    13
>> Volume = pi * r^2 * h
Volume =
  1.0210e+003
>> Area = 2 * pi * r * (r + h)
Area =
  565.4867
```

## Useful MATLAB commands

Command	Description
clc	Clears the Command window.
clear	Removes all variables from memory.
clear var1 var2	Removes the variables var1 and var2 from memory.
exist('name')	Determines if a file or variable exists having the name 'name'.
quit	Stops MATLAB.
who	Lists the variables currently in memory.
whos	Lists the current variables and sizes, and indicates if they have imaginary parts.
:	Colon; generates an array having regularly spaced elements.
,	Comma; separates elements of an array.
;	Semicolon; suppresses screen printing; also denotes a new row
	in an array.
	Ellipsis; continues a line.

## Vectors and Matrices (Arrays)

- So far we used MATLAB variables to store a single value.
- We can also create MATLAB arrays that hold multiple values
  - List of values (1D array) called **Vector**
  - Table of values (2D array) called **Matrix**
- Vectors and matrices are used extensively when solving engineering and science problems.

## Row Vector

- Row vectors are special cases of matrices.
- This is a 7-element row vector  $(1 \times 7 \text{ matrix})$ .
- Defined by enclosing numbers within square brackets [ ] and separating them by , or a space.

```
>> C = [10, 11, 13, 12, 19, 16, 17]

C =

10    11    13    12    19    16    17

>> C = [10    11    13    12    19    16    17]

C =

10    11    13    12    19    16    17
```



## Column Vector

- Column vectors are special cases of matrices.
- This is a 7-element column vector ( $7 \times 1$  matrix).
- Defined by enclosing numbers within [ ] and separating them by semicolon;

```
>> R = [10; 11; 13; 12; 19; 16; 17]

R =

10
11
13
12
19
16
17
```



## Matrix

- This is a  $3 \times 4$ -element matrix.
- It has 3 rows and 4 columns (dimension  $3 \times 4$ ).
- Spaces or commas separate elements in different columns, whereas semicolons separate elements in different rows.
- A dimension  $n \times n$  matrix is called *square* matrix.

>>	M	=	[1,		3,	2,	9;	; (	ŝ,	7,	8,	-	;	7,	4,	6,	0]
M =	=																
		1			3		2			9							
		6		1	7		8			1							
		7			4		6			0							
>>	M	=	[1	3	2	9;	6	7	8	1;	7	4	6	0]			
M =	=																
		1			3		2			9							
		6		1	7		8			1							
		7			4		6			0							



## Transpose of a Matrix

- The transpose operation interchanges the rows and columns of a matrix.
- For an  $m \times n$  matrix **A** the new matrix **A**<sup>T</sup> (read "A transpose") is an  $n \times m$  matrix.
- In MATLAB, the A' command is used for transpose.

$$\mathbf{A} = \begin{bmatrix} -2 & 6 \\ -3 & 5 \end{bmatrix}$$

$$= \begin{bmatrix} -2 & 6 \\ -3 & 5 \end{bmatrix} \qquad \mathbf{A}^T = \begin{bmatrix} -2 & -3 \\ 6 & 5 \end{bmatrix}$$

## Exercise

```
>> B = [5 6 7 8]
B =
5 6 7 8

>> B'
ans =
5
6
7
8
```

- What happens to a row vector when transposed?
- What happens to a column vector when transposed?

## Useful Functions

length(A)	Returns either the number of elements of A if A
	is a vector or the largest value of <i>m</i> or <i>n</i> if A is an
	$m \times n$ matrix
size(A)	Returns a row vector [m n] containing the
	sizes of the $m \times n$ matrix A.
max(A)	For vectors, returns the largest element in A.
	For matrices, returns a row vector containing the
	maximum element from each column.
	If any of the elements are complex, max (A)
	returns the elements that have the largest
	magnitudes.
$[v,k] = \max(A)$	Similar to max (A) but stores the maximum
	values in the row vector v and their indices in
	the row vector k.
min(A)	Like max but returns minimum values.
and	
[v,k] = min(A)	

## More Useful Functions

sort(A)	Sorts each column of the array A in ascending
	order and returns an array the same size as A.
sort(A,DIM,MODE)	Sort with two optional parameters:
	DIM selects a dimension along which to sort.
	MODE is sort direction ('ascend' or 'descend').
sum(A)	Sums the elements in each column of the array A
	and returns a row vector containing the sums.
sum(A,DIM)	Sums along the dimension DIM.



#### Exercises

```
>> X = [4 9 2 5]
X =
>> length(X)
ans =
>> size(X)
ans =
     1
>> min(X)
ans =
```

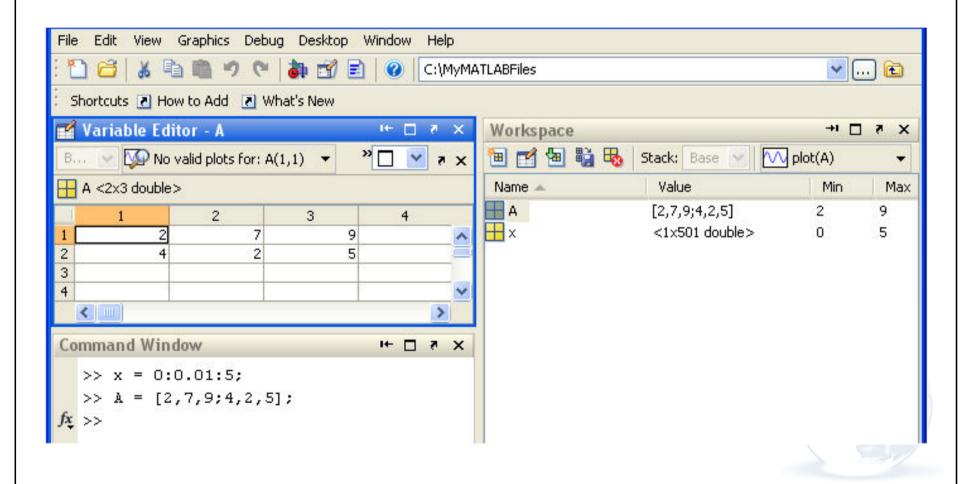
```
>> M = [1 6 4; 3 7 2]
>> size(M)
>> length(M)
>> \max(M)
>> [a,b] = max(M)
>> sort(M)
>> sort(M, 1, 'descend')
>> sum(M)
\gg sum(M, 2)
```

#### Solution

```
>> M = [1 6 4; 3 7 2]
M =
>> size(M)
ans =
>> length(M)
ans =
     3
\gg max(M)
ans =
\gg [a,b] = max(M)
```

```
>> sort(M)
ans =
                 2
>> sort(M, 1, 'descend')
ans =
>> sum(M)
ans =
    4 13
                6
\gg sum(M, 2)
ans =
    11
    12
```

## The Variable Editor [from Workspace or openyar ('A')]



## Creating Big Matrices

- What if you want to create a Matrix that contains 1000 element (or more)?
- Writing each element by hand is difficult, time-consuming and error-prone.
- MATLAB allows simple ways to quickly create matrices, such as:
- Using the colon: operator (very popular).
- Using linspace() and logspace() functions (less popular, but useful).

## Using the colon operator

- MATLAB command X = J:D:K creates vector X = [J, J+D, ..., J+m\*D] where m = fix((K-J)/D).
- In other words, it creates a vector X of values **starting** at J, **ending** with K, and with **spacing** D.
- Notice that the last element is K if K J is an integer multiple of D. If not, the last value is *less than* J.
- MATLAB command J:K is the same as J:1:K.
- Note:
  - J:K is empty if J > K.
  - J:D:K is empty if D == 0, if D > 0 and J > K, or if D < 0 and J < K.

## Example 1



## Example 2

```
>> x = 7:-1:2
x =
>> x = 5:0.1:5.9
x =
 Columns 1 through 5
   5.0000 5.1000 5.2000 5.3000 5.4000
 Columns 6 through 10
   5.5000 5.6000 5.7000 5.8000 5.9000
>> y = 5:0.1:5.9; % what happened here?!
>>
>> % now create a 'column' vector from 1 to 10 using :
```

#### Alternatives to colon

- linspace command creates a linearly spaced row vector, but instead you specify the number of values rather than the increment.
- The syntax is linspace(x1, x2, n), where x1 and x2 are the lower and upper limits and n is the number of points.
- If n is omitted, the number of points defaults to 100.
- logspace command creates an array of logarithmically spaced elements.
- Its syntax is logspace (a,b,n), where n is the number of points between 10<sup>a</sup> and 10<sup>b</sup>.
- If n is omitted, the number of points defaults to 50.

## Exercise

```
>> x = linspace(5,8,3)

x =

5.0000 6.5000 8.0000

>> x = logspace(-1,1,4)

x =

0.1000 0.4642 2.1544 10.0000
```

## Special: ones, zeros, rand

```
>> a = ones(2,4)
>> b = zeros(4, 3) % null matrix
h =
>> c = rand(2, 4)
   0.8147 0.1270 0.6324 0.2785
   0.9058 0.9134 0.0975 0.5469
% random values drawn from the standard
% uniform distribution on the open
```

% interval(0,1)

```
>> eye(4) % identity matrix
ans =
>> A = [1 2 3; 4 5 6; 7 8 9]
A =
                   3
>> I = eye(3)
T_{\cdot} =
>> A*I
ans =
                   6
```

## Null and Identity Matrix

$$0A = A0 = 0$$
$$IA = AI = A$$

#### Matrix Determinant & Inverse

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$
$$= a(ei - fh) - b(di - fg) + c(dh - eg)$$
$$= aei + bfg + cdh - ceg - bdi - afh.$$

$$\begin{vmatrix} a_{32} & a_{33} & a_{32} & a_{22} & a_{23} \end{vmatrix}$$

$$\begin{vmatrix} a_{23} & a_{21} & a_{11} & a_{13} & a_{11} \\ a_{33} & a_{31} & a_{31} & a_{33} & a_{21} \end{vmatrix}$$

$$\begin{vmatrix} a_{21} & a_{22} & a_{21} & a_{11} & a_{12} \\ a_{31} & a_{32} & a_{31} & a_{32} & a_{21} \end{vmatrix}$$

```
\Rightarrow A = [1 2 3; 2 3 1; 3 2 1]
>> det(A) % determinant
ans =
   -12
>> inv(A) % inverse
ans =
   -0.0833 \quad -0.3333 \quad 0.5833
  -0.0833 0.6667 -0.4167
   0.4167
             -0.3333 0.0833
>> A^-1
ans =
   -0.0833 \quad -0.3333 \quad 0.5833
  -0.0833 0.6667
                        -0.4167
   0.4167
             -0.3333
                       0.0833
```

## Accessing Matrix Elements

```
>> C = [10, 11, 13, 12, 19, 16, 17]
   10 11 13 12 19 16
                                     17
>> C(4)
ans =
   12
>> C(1,4)
ans =
   12
>> C(20)
??? Index exceeds matrix dimensions.
```

## Notes

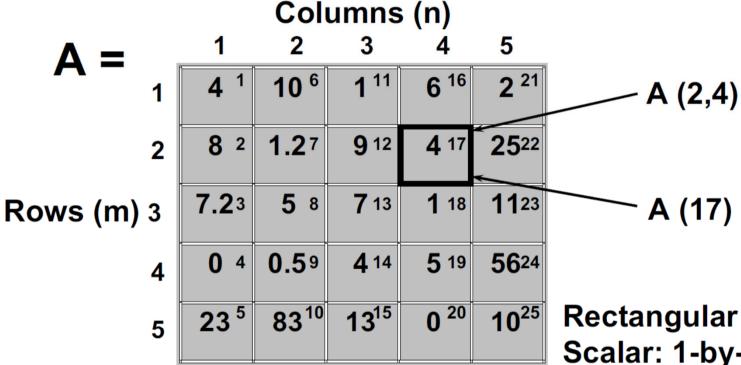
- Use () not [] to access matrix elements.
- The row and column indices are NOT zero-based, like in C/C++.
- The first is row number, followed by the column number.
- For matrices and vectors, you can use one of three indexing methods: matrix row and column indexing; linear indexing; and logical indexing.
- You can also use ranges (shown later).

#### Accessing Matrix Elements

```
>> M = [1, 3, 2, 9; 6, 7, 8, 1; 7, 4, 6, 0]
M =
>> M(2, 3)
ans =
>> M(3, 1)
ans =
>> M(0, 1)
??? Subscript indices must either be real
positive integers or logicals.
>> M(9)
ans =
```



## Matrix Linear Indexing



 $A = 5 \times 5$  matrix.

**Rectangular Matrix:** 

Scalar: 1-by-1 array

**Vector: m-by-1 array** 

1-by-n array

Matrix: m-by-n array

## Indexing: Sub-matrix

- v(2:5) represents the second through fifth elements i.e., v(2), v(3), v(4), v(5).
- v(2:end) represents the second till last element of v.
- v(:) represents all the row or column elements of vector v.
- A(:, 3) denotes all elements in the third column of matrix A.
- A(:, 2:5) denotes all elements in the second through fifth columns of A.
- A(2:3,1:3) denotes all elements in the second and third rows that are also in the first through third columns.
- A (end, :) all elements of the last row in A.
- A(:, end) all elements of the last column in A.
- v = A(:) creates a vector v consisting of all the columns of A stacked from first to last.

#### Exercise

```
>> v = 10:10:70
V =
    10
           20
                 30
                        40
                               50
                                     60
                                            70
>> v(2:5)
ans =
    20
           30
                 40
                        50
>> v(2:end)
ans =
          30
                 40
                        50
    20
                               60
                                     70
>> v(:)
ans =
    10
    20
    30
    40
    50
    60
    70
```



## Exercise

```
>> A = [4 10 1 6 2; 8 1.2 9 4 25; 7.2 5 7 1
11; 0 0.5 4 5 56; 23 83 13 0 10]
A =
   4.0000 10.0000 1.0000 6.0000
                                    2.0000
         1.2000 9.0000 4.0000 25.0000
   8.0000
   7.2000
          5.0000 7.0000 1.0000 11.0000
          0.5000 4.0000 5.0000 56.0000
  23.0000 83.0000 13.0000
                                   0.0000
>> A(:,3)
ans =
    13
>> A(:,2:5)
ans =
             1.0000
   10.0000
                       6.0000
                                 2.0000
   1.2000
            9.0000
                       4.0000
                                25.0000
  5.0000
           7.0000
                       1.0000
                               11.0000
0.5000
           4.0000
                       5.0000
                                56.0000
   83.0000
            13.0000
                               10.0000
Like of the State
>> A(2:3,1:3)
ans =
             1.2000
                       9.0000
    8.0000
    7.2000
             5.0000
                       7.0000
```

```
>> A(end,:)
ans =
          83
    23
                 13
                         0
                              10
>> A(:,end)
ans =
    25
    11
    56
    10
>> v = A(:)
\nabla =
    4.0000
    8.0000
    7.2000
          0
   23.0000
   10.0000
    1.2000
    5.0000
    0.5000
   83.0000
    1.0000
    9.0000
    7.0000
    4.0000
   13.0000
    6.0000
    4.0000
    1.0000
    5.0000
    2.0000
   25.0000
   11.0000
   56.0000
   10.0000
```

## Linear indexing: Advanced

```
>> A = 5:5:50
A =
 5 10 15 20 25 30 35 40 45 50
>> A([1 3 6 10])
ans =
      15 30 50
>> A([1 3 6 10]')
ans =
      15 30 50
>> A([1 3 6; 7 9 10])
ans =
      15
           30
   35
         45
           50
% indexing into a vector with a nonvector,
the shape of the indices is honored
```

## Linear indexing is useful: find

```
\Rightarrow A = [1 2 3; 4 5 6; 7 8 9]
A =
  B = find(A > 5) % returns linear index
B =
   A(B) % same as A(find(A > 5))
ans =
     9
```

## Advanced: Logical indexing

```
>> A = [1 2 3; 4 5 6; 7 8 9]
A =

      1
      2
      3

      4
      5
      6

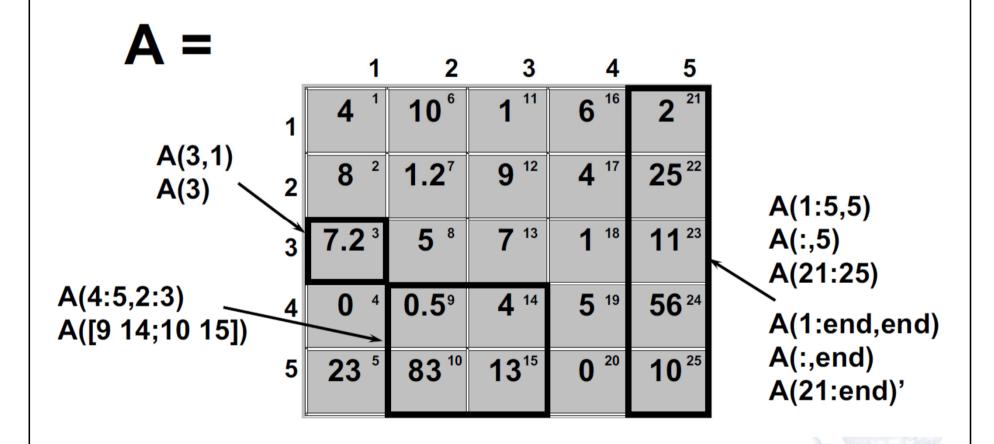
      7
      8
      9

>> B = logical([0 1 0; 1 0 1; 0 0 1])
>> A(B)
ans =
          6
```

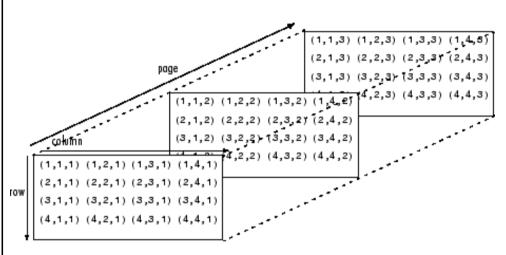
## Logical indexing is also useful!

```
>> A = [1 2 3; 4 5 6; 7 8 9]
>> B = (A > 5) % true or false
>> A(B) % same as A(A > 5)
ans =
```

# Subscripting Examples



## More dimensions possible



- The first index references array dimension 1, the row.
- The second index references dimension 2, the column.
- The third index references dimension 3, the page.

>> rand(4,4,3)				
ans(:,:,1) =				
0.3922 0.6555	0.7060 0.0318 0.2769 0.0462	0.0971 0.8235 0.6948 0.3171	0.9502 0.0344 0.4387 0.3816	
ans(:,:,2) =				
	0.4456 0.6463 0.7094 0.7547	0.2760 0.6797 0.6551 0.1626	0.1190 0.4984 0.9597 0.3404	
ans(:,:,3) =				
0.5853 0.2238 0.7513 0.2551	0.5060 0.6991 0.8909 0.9593	0.5472 0.1386 0.1493 0.2575	0.8407 0.2543 0.8143 0.2435	

# Extending Matrices

- You can add extra elements to a matrix by creating them directly using ()
- Or by concatenating (appending) them using [ , ] or [ ; ]
- If you don't assign array elements, MATLAB gives them a default value of 0

```
>> h = [12 11 14 19 18 17]
h =
    12 11 14 19 18 17

>> h = [h 13]
h =
    12 11 14 19 18 17 13

>> h(10) = 1
h =
    12 11 14 19 18 17 13 0 0 1
```



## Example

```
>> a = [2 \ 4 \ 20]
a =
        4
                 20
>> b = [9, -3, 6]
     9
>> [a b]
ans =
                 20
                              -3
>> [a, b]
ans =
                 20
>> [a; b]
ans =
                 20
     9
          -3
                  6
```

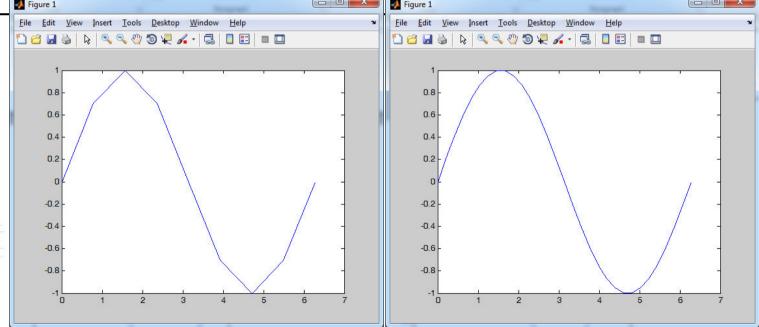


## Functions on Arrays

- Standard MATLAB functions (sin, cos, exp, log, etc) can apply to vectors and matrices as well as scalars.
- They operate on array arguments to produce an array result the same size as the array argument x.
- These functions are said to be vectorized functions.
- In this example y is  $[\sin(1), \sin(2), \sin(3)]$
- So, when writing functions (later lectures) remember input might be a vector or matrix.



```
>> x = [1, 2, 3]
x =
1 2 3
>> y = sin(x)
y =
0.8415 0.9093 0.1411
```



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## Matrix vs. Array Arithmetic

- Multiplying and dividing vectors and matrices is different than multiplying and dividing scalars (or arrays of scalars).
- This is why MATLAB has two types of arithmetic operators:
  - Array operators: where the arrays operated on have the same size. The operation is done element-by-element (for all elements).
  - Matrix operators: dedicated for matrices and vectors. Operations are done using the matrix as a whole.

## Matrix vs. Array Operators

Symbol	Operation	Symbol	Operation
+	Matrix addition	+	Array addition
_	Matrix subtraction	_	Array subtraction
*	Matrix multiplication	• *	Array multiplication
/	Matrix division	• /	Array division
	Left matrix division	. \	Left array division
^	Matrix power	• ^	Array power

<sup>\*</sup> idivide() allows integer division with rounding options



#### Matrix/Array Addition/Subtraction

- Matrices and arrays are treated the same when adding and subtracting.
- The two matrices should have identical size.
- Their sum or difference has the same size, and is obtained by adding or subtracting the corresponding elements.
- Addition and subtraction are associative and commutative.

$$\begin{bmatrix} 6 & -2 \\ 10 & 3 \end{bmatrix} + \begin{bmatrix} 9 & 8 \\ -12 & 14 \end{bmatrix} = \begin{bmatrix} 15 & 6 \\ -2 & 17 \end{bmatrix}$$

$$(A + B) + C = A + (B + C)$$
  
 $A + B + C = B + C + A = A + C + B$ 

# More ...

• A scalar value at either side of the operator is expanded to an array of the same size as the other side of the operator.

$$[6,3] + 2 = [8,5]$$
  
 $[8,3] - 5 = [3,-2]$   
 $[6,5] + [4,8] = [10,13]$   
 $[6,5] - [4,8] = [2,-3]$ 



#### Array Multiplication

- Element-by-element multiplication.
- Only for arrays that are the same size.
- Use the . \* operator not the \* operator.
- Not the same as matrix multiplication.
- Useful in students make the mistake of using \*

$$\mathbf{A} = \begin{bmatrix} 11 & 5 \\ -9 & 4 \end{bmatrix} \qquad \mathbf{B} = \begin{bmatrix} -7 & 8 \\ 6 & 2 \end{bmatrix}$$

$$C = A.*B$$

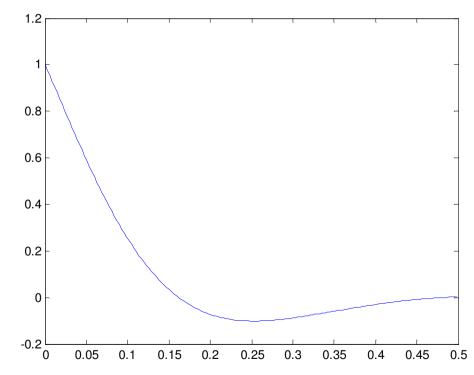
Useful in programming, but 
$$C = \begin{bmatrix} 11(-7) & 5(8) \\ -9(6) & 4(2) \end{bmatrix} = \begin{bmatrix} -77 & 40 \\ -54 & 8 \end{bmatrix}$$

#### Using Array Multiplication (Plot)

- Plot the following function:
- Notice the use of .\* operator

$$y(t) = e^{-8t} \sin\left(9.7t + \frac{\pi}{2}\right)$$

```
>> t = 0:0.003:0.5;
>> y = exp(-8*t).*sin(9.7*t+pi/2);
>> plot(t,y)
```



#### Matrix Multiplication

- If A is an n × m matrix and B is a m × p matrix, their matrix product AB is an n × p matrix, in which the m entries across the rows of A are multiplied with the m entries down the columns of B.
- In general, AB ≠ BA for matrices. Be extra careful.

$$m \times p$$
 matrix, their matrix product AB 
$$\begin{bmatrix} 2 & 7 \\ 6 & -5 \end{bmatrix} \begin{bmatrix} 3 \\ 9 \end{bmatrix} = \begin{bmatrix} 2(3) + 7(9) \\ 6(3) - 5(9) \end{bmatrix} = \begin{bmatrix} 69 \\ -27 \end{bmatrix}$$

across the rows of A are multiplied with 
$$\begin{bmatrix} u_1 & u_2 & u_3 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = u_1w_1 + u_2w_2 + u_3w_3$$
 the  $m$  entries down

#### Matrix Multiplication

$$\begin{bmatrix} 6 & -2 \\ 10 & 3 \\ 4 & 7 \end{bmatrix} \begin{bmatrix} 9 & 8 \\ -5 & 12 \end{bmatrix} = \begin{bmatrix} (6)(9) + (-2)(-5) & (6)(8) + (-2)(12) \\ (10)(9) + (3)(-5) & (10)(8) + (3)(12) \\ (4)(9) + (7)(-5) & (4)(8) + (7)(12) \end{bmatrix}$$

$$= \begin{bmatrix} 64 & 24 \\ 75 & 116 \\ 1 & 116 \end{bmatrix}$$

$$(2.4-4)$$

$$3\begin{bmatrix} 2 & 9 \\ 5 & -7 \end{bmatrix} = \begin{bmatrix} 6 & 27 \\ 15 & -21 \end{bmatrix}$$

$$>>A = [2,9;5,-7];$$

$$>>3*A$$

#### Array Division

- Element-by-element division.
- Only for arrays that are the same size.
- Use the ./ operator not the / operator.
- Not the same as matrix division.
- Useful in mistake of using /

$$\mathbf{A} = \begin{bmatrix} 24 & 20 \\ -9 & 4 \end{bmatrix} \qquad \mathbf{B} = \begin{bmatrix} -4 & 5 \\ 3 & 2 \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} -4 & 5 \\ 3 & 2 \end{bmatrix}$$

$$C = A./B$$

Useful in programming, but 
$$C = \begin{bmatrix} 24/(-4) & 20/5 \\ -9/3 & 4/2 \end{bmatrix} = \begin{bmatrix} -6 & 4 \\ -3 & 2 \end{bmatrix}$$
 students make the

#### Matrix Division

• An  $n \times n$  square matrix **B** is called invertible (also nonsingular) if there exists an  $n \times n$  matrix **B**<sup>-1</sup> such that their multiplication is the identity matrix.

$$\frac{A}{B} = A B^{-1}$$

$$B B^{-1} = I$$

$$A = \begin{bmatrix} 1 & 5 & 6 \\ 6 & 5 & 4 \\ 4 & 6 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 5 & 6 \\ 6 & 5 & 4 \\ 4 & 6 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 5 & 6 \\ 6 & 5 & 4 \\ 4 & 6 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 3 & 2 & 15 \\ 2 & 15 & 15 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 3 & 2 & 15 \\ 2 & 15 & 15 \end{bmatrix}$$

### Matrix Division

```
>> A = [1 2 3; 3 2 1; 2 1 3];
>> B = [4 5 6; 6 5 4; 4 6 5];
>> A/B
ans =
   0.7000
            -0.3000
   -0.3000
          0.7000
                        0.0000
    1.2000
           0.2000
                       -1.0000
>> format rat
>> A/B
ans =
     7/10
                 -3/10
    -3/10
                  7/10
     6/5
                  1/5
```

### Matrix Left Division

- Use the left division operator (\) (back slash) to solve sets of linear algebraic equations.
- If A is n × n matrix and B is a column vector with n elements, then x = A\B is the solution to the equation Ax = B.
- A warning message is displayed if A is badly scaled or nearly singular.

```
6x + 12y + 4z = 70

7x - 2y + 3z = 5

2x + 8y - 9z = 64

>>A = [6,12,4;7,-2,3;2,8,-9];

>>B = [70;5;64];

>>Solution = A\B

Solution = 3
```

scaled or nearly singular. The solution is x = 3, y = 5, and z = -2.

## Homework: Mesh Analysis

KVL @ mesh 2:

$$1(i_2 - i_1) + 2i_2 + 3(i_2 - i_3) = 0$$

KVL @ supermesh 1/3:

$$-7 + 1(i_1 - i_2) + 3(i_3 - i_2) + 1i_3 = 0$$

@ current source:

$$7 = i_1 - i_3$$

*Three* equations:

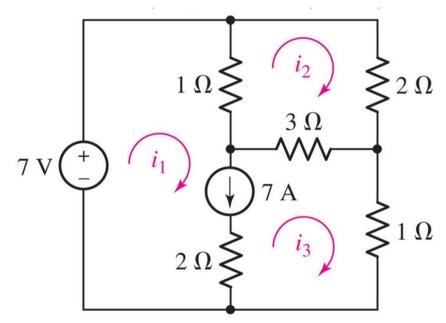
$$-i_1 + 6i_2 - 3i_3 = 0$$

$$i_1 - 4i_2 + 4i_3 = 7$$

$$i_1 - i_3 = 7$$

Solution:

$$i_1 = 9A$$
,  $i_2 = 2.5A$ ,  $i_3 = 2A$ 



## Just between us...

• Matrix division and matrix left division are related in MATLAB by the equation:

$$B/A = (A' \setminus B')' % reversing$$

• To see the details, type: doc mldivide or type: doc mrdivide

## Array Left Division

- The array left division A.\B (back slash) divides each entry of B by the corresponding entry of A.
- Just like B./A
- A and B must be arrays of the same size.
- A scalar value for either
   A or B is expanded to
   an array of the same
   size as the other.

# Array Power

$$B = A.^3$$

$$\mathbf{B} = \begin{bmatrix} 4^3 & (-5)^3 \\ 2^3 & 3^3 \end{bmatrix} = \begin{bmatrix} 64 & -125 \\ 8 & 27 \end{bmatrix} \qquad \begin{array}{c} 3. \text{ ^p} \\ 3.0. \text{ ^p} \end{array}$$

$$p = [2, 4, 5]$$

$$3.^{2}[2,4,5]$$

# Matrix Power

- A^k computes matrix power (exponent).
- In other words, it multiplies matrix **A** by itself *k* times.
- The exponent *k* requires a positive, real-valued integer value.
- Remember: this is repeated matrix
   multiplication

### Matrix Manipulation Functions

- diag: Diagonal matrices and diagonal of a matrix.
- det: Matrix determinant
- inv: Matrix inverse
- cond: Matrix condition number (for inverse)
- fliplr: Flip matrices left-right
- flipud: Flip matrices up and down
- repmat: Replicate and tile a matrix



## Matrix Manipulation Functions

- rot90: rotate matrix 90°
- tril: Lower triangular part of a matrix
- triu: Upper triangular part of a matrix
- cross: Vector cross product
- dot: Vector dot product
- eig: Evaluate eigenvalues and eigenvectors
- rank: Rank of matrix



- Define matrix A of dimension 2 by 4 whose (i,j) entries are A(i,j) = i+j
- Extract two 2 by 2 matrices A1 and A2 out of matrix A.
  - A1 contains the first two columns of A
  - A2 contains the last two columns of A
- Compute matrix B to be the sum of A1 and A2
- Compute the eigenvalues and eigenvectors of B
- Solve the linear system B x = b, where b has all entries = 2
- Compute the determinant of B, inverse of B, and the condition number of B
- NOTE: Use only MATLAB native functions for all above.

#### Solution

```
>> A = [0 1 2 3; 1 2 3 4]
A =
>> A1 = A(:,1:2)
A1 =
>> A2 = A(:, 3:4)
A2 =
>> B = A1 + A2
```

```
>> b = [2; 2]
b =
>> B\b
ans =
   -1.0000
    1.0000
>> det(B)
ans =
    -4
>> inv(B)
ans =
   -1.5000 1.0000
    1.0000 -0.5000
>> cond(B)
ans =
   17.9443
```

# Homework

- Solve as many problems from Chapter 1 as you can
- Suggested problems:
- 1.3, 1.8, 1.15, 1.26, 1.30
- Solve as many problems from Chapter 2 as you can
- Suggested problems:
- 2.3, 2.10, 2.13, 2.25, 2.26

